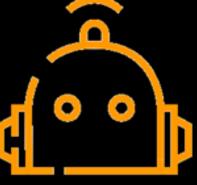
# The Robotic Edge

# The Role of the Cloud In the Future of Robotics



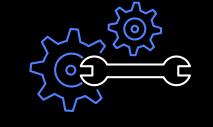
Roger S. Barga, PhD **GM**, AWS Robotics

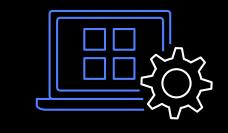




# Robotics development and deployment challenges







Multi-domain expertise required to build robots

**Iterative development** to get it right



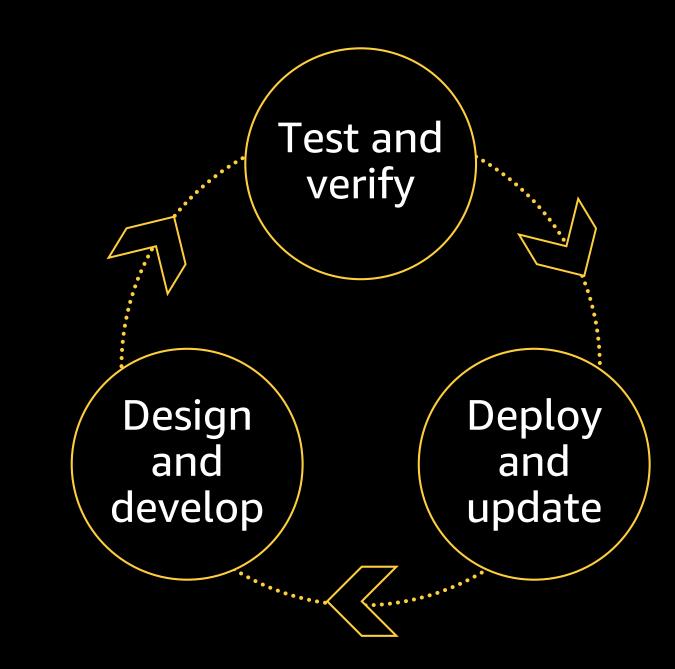
Limited robot hardware available for testing



**Deployment and updates** need to be managed

### Configuration management is hard

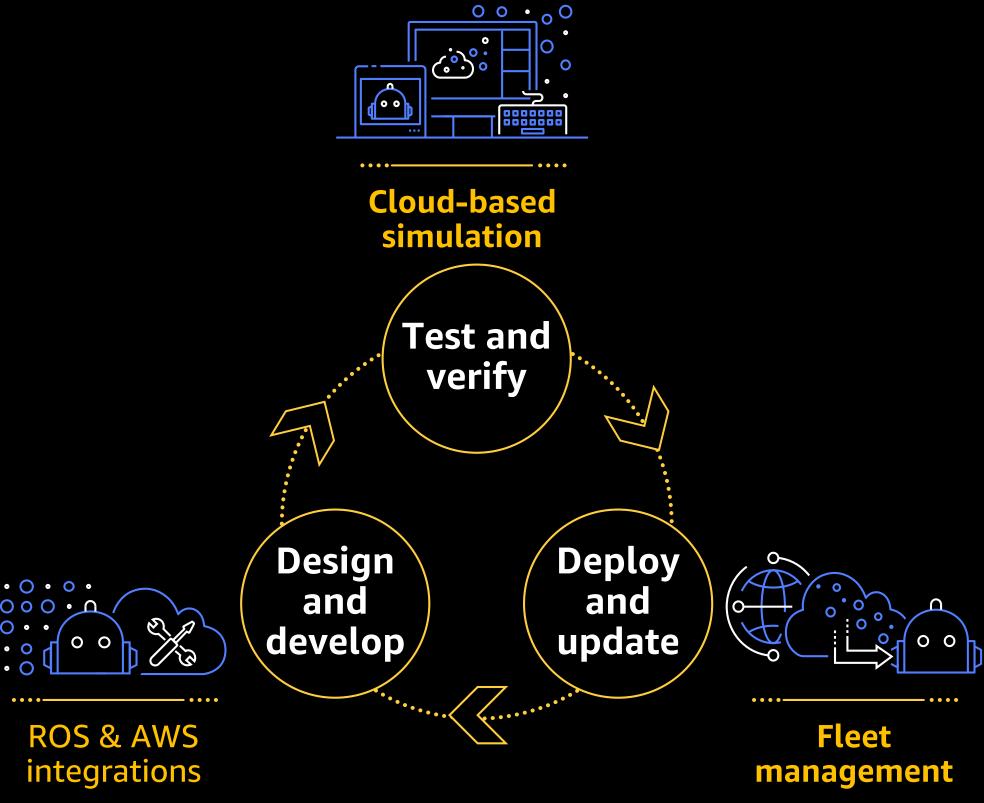
# Robotics application development



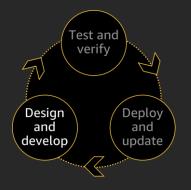
# **AWS** RoboMaker

a cloud service to build, test, deploy, and manage robotics applications at cloud scale

0 0 0



# **Design and Develop** robotics applications and functionality







### Agile development of robotics application requires software reuse and iterative development



# ROS2

Core architectural change between ROS 1 and ROS 2:

Addition of ROS Middleware (RMW) & Data Distribution Service (DDS).

- Security
- Reliability
- Determinism

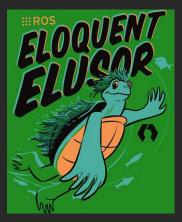
| User Code                        | Application          |                    |          |                   |  |
|----------------------------------|----------------------|--------------------|----------|-------------------|--|
| User Code                        | MASTER Node 1 Node 2 |                    | Node N   |                   |  |
|                                  | actionlib            | dynamic parameters | nodelets |                   |  |
| Middleware &<br>Client Libraries | roscpp (C++)         |                    |          | rospy<br>(Python) |  |
|                                  | TCPROS/UDPROS        |                    |          |                   |  |
| OS Layer                         | Linux                |                    |          |                   |  |

| 2 | User Code               | Application                      |                |                |  |
|---|-------------------------|----------------------------------|----------------|----------------|--|
|   |                         | Node 1                           | Node 2         | Node N         |  |
|   | Middleware &            | rclcpp (C++)                     | rclpy (Python) | rcljava (Java) |  |
|   |                         | ROS Client Library (rcl)         |                |                |  |
|   | <b>Client Libraries</b> | ROS Abstraction Middleware (RMW) |                |                |  |
|   |                         | Connext DDS                      | FastRTPS       | OpenSplice DDS |  |
|   | OS Layer                | Linux                            | OS X           | Windows        |  |



ROS 1

ROS 2



## **AWS Robotics** Select contributions to ROS2





Quality of Service (QoS) Features for Topics





Cross-Compilation Tools





rosbag2 splitting, compression



### ROS2 Launch Sandboxing Extension

Nodes and example applications for AWS integration

Runtime Analysis Tools Address & Thread Sanitizers

## **Design and** Develop ROS and ROS packages for AWS integrations

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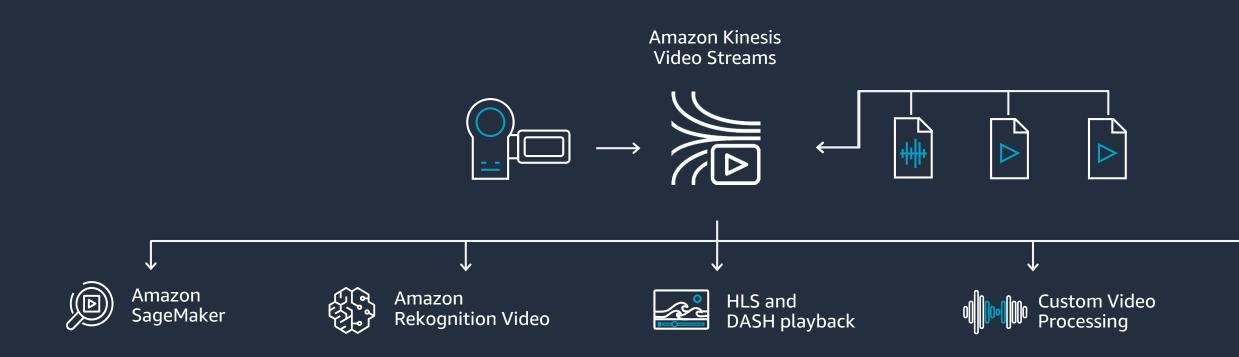
Support for ROS Kinetic, ROS Melodic, ROS 2 Dashing (beta)

Native ROS packages for AWS services: Amazon S3 for secure, scalable storage Amazon **CloudWatch** for logging and metrics Amazon **Rekognition** for image and video recognition Amazon Kinesis for video streaming Amazon Lex and Amazon Polly for voice recognition and text-speech conversion

# Amazon Kinesis Video Streams



Welcome to Amazon Go and the world's most advanced shopping technology. No lines, no checkout just grab and go!



### Ingests, stores, and indexes video streams from millions of cameras

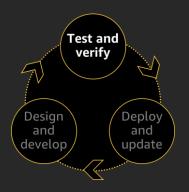
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Third-party partners





## **Test & Verify** simulations at cloud scale



Simulate your environment



Test alternative scenarios



## Use simulation to replicate your environment, test application, and optimize usage of robot resources

### Drive optimization

## **Test & Verify** cloud-based simulations

 $\bigcirc$  $\dot{\bigcirc}$  Pre-built virtual 3D worlds provided out of box, or bring your own

Zero infrastructure to provision, configure, or manage

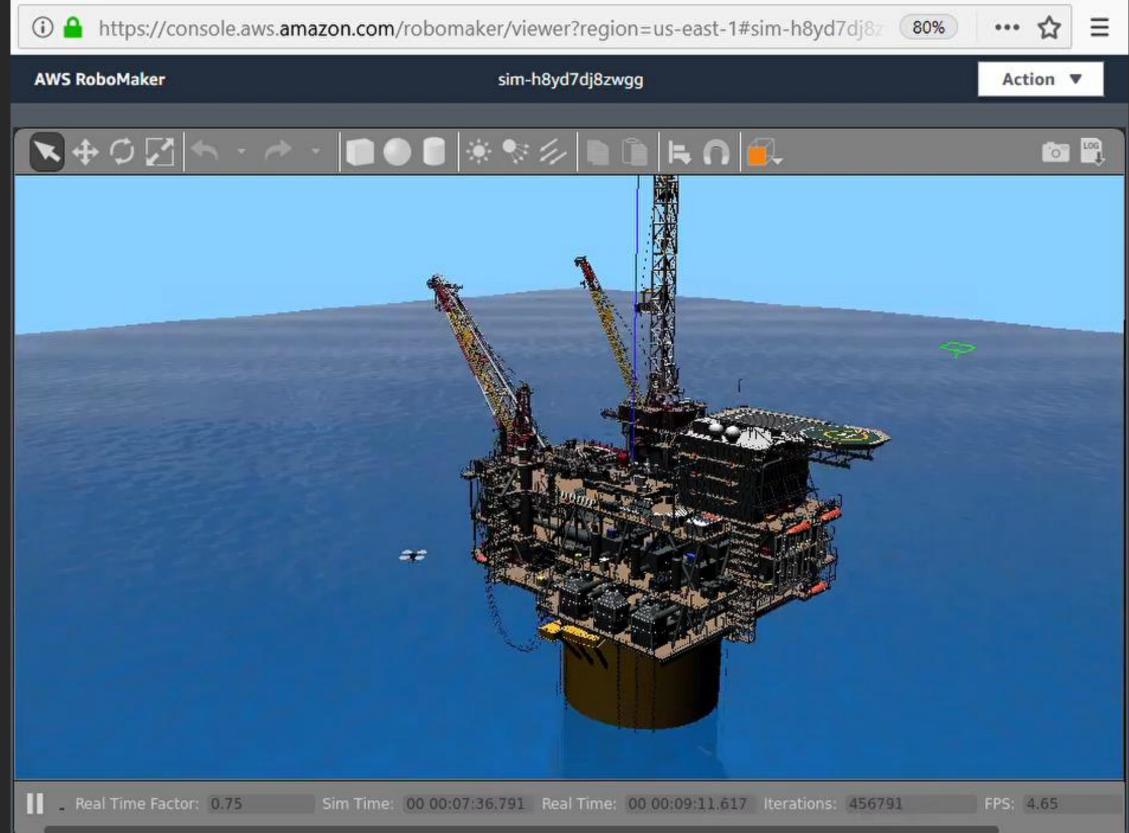
Run multiple simulations in parallel

Auto-scale based on simulation complexity

Pay-as-you-go simulation resource consumption

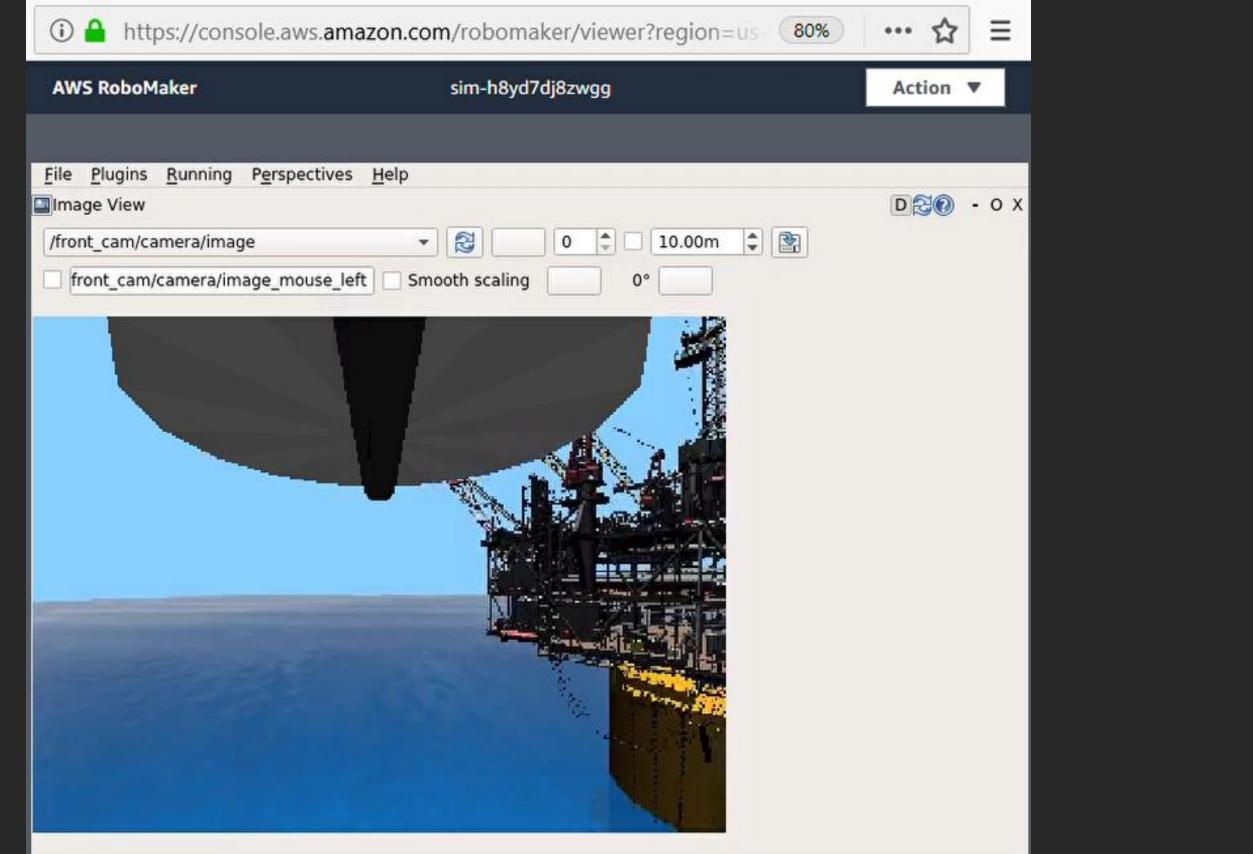




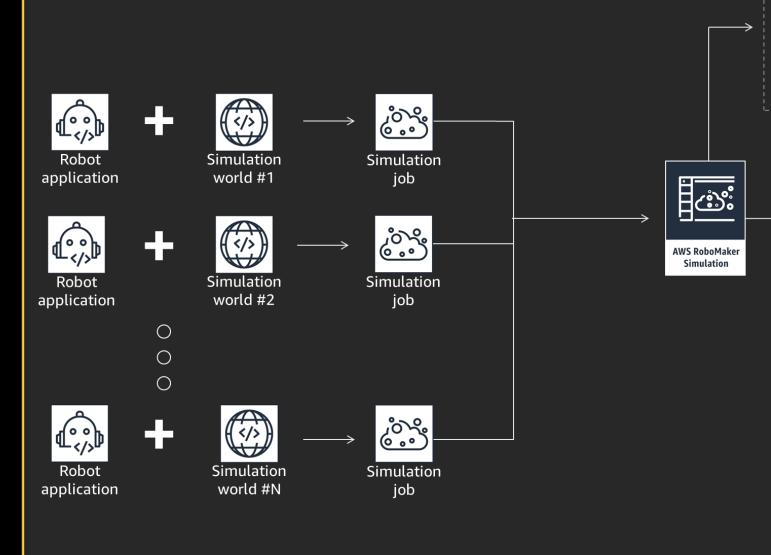


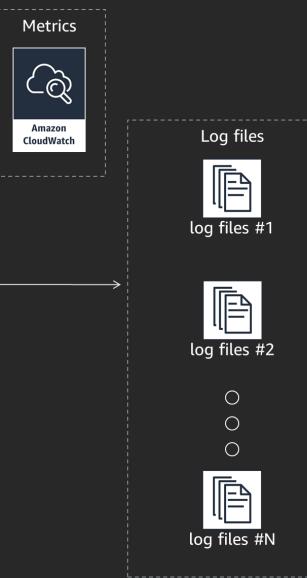


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**Test & Verify** Able to run thousands of concurrent simulations





# 



# iRobot accelerates robot regression testing

### Need

Test coverage for different floor layouts and scenarios Improve code release speed

### Challenges

Costly and time consuming to test Limited test cases and coverage Late bug discovery in the field

### Solution

iRobot built a CI/CD pipeline for large-scale and automated testing using RoboMaker's simulation service More than 40 automated tests on each code commit and more than 500 automated tests for each release candidate Much faster testing and release cycle (1 hour versus 3 weeks for testing 70 complex localization scenarios)

# In Production

- Within 3 months!
- 5,000 missions a month
- Gating submissions
- Catching issues
- Higher quality mainline
- Developers want more

| ile | <u>E</u> dit <u>C</u> ame  | ra <u>V</u> iew   | <u>W</u> indow | <u>H</u> elp |
|-----|--|-------------------|----------------|--------------|
|     | orld Insert<br>GUI<br>Scene<br>Spherical Coord<br>Hay de<br>Atmosphere<br>Wind<br>Models<br>Lights | Layers<br>dinates |                |              |
| Pro | perty  | Value             |                |              |
|     | physics engi   | ODE               |                |              |
| 17  | enable physi   |                   |                |              |
|     | real time up   | 0.000000          |                |              |
|     | max step size  | 0.005000          |                |              |
| D   | gravity  |                   | (**<br>11      |              |
|     | magnetic field   |                   |                |              |
|     | solver   |                   |                |              |
|     | iterations   | 200               |                |              |
|     | SOR  | 1.300000          |                |              |
|     | constraints  |                   |                |              |



n Time: 00



## **Test & Verify** multi-robot simulations

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Simulate multiple robots within the same environment

Connect multiple simulations to a central fleet-management software to test multi-robot scenarios

Simulate inter-robot interactions or missions across robots



# Bastian Solutions uses Robo Maker to simulate multi-robot fleets

### Problem statement

Bastian Solutions enables orchestration of a fleet of robots

Software testing currently requires physical robots; practical limitation of 8–10 robots in test lab

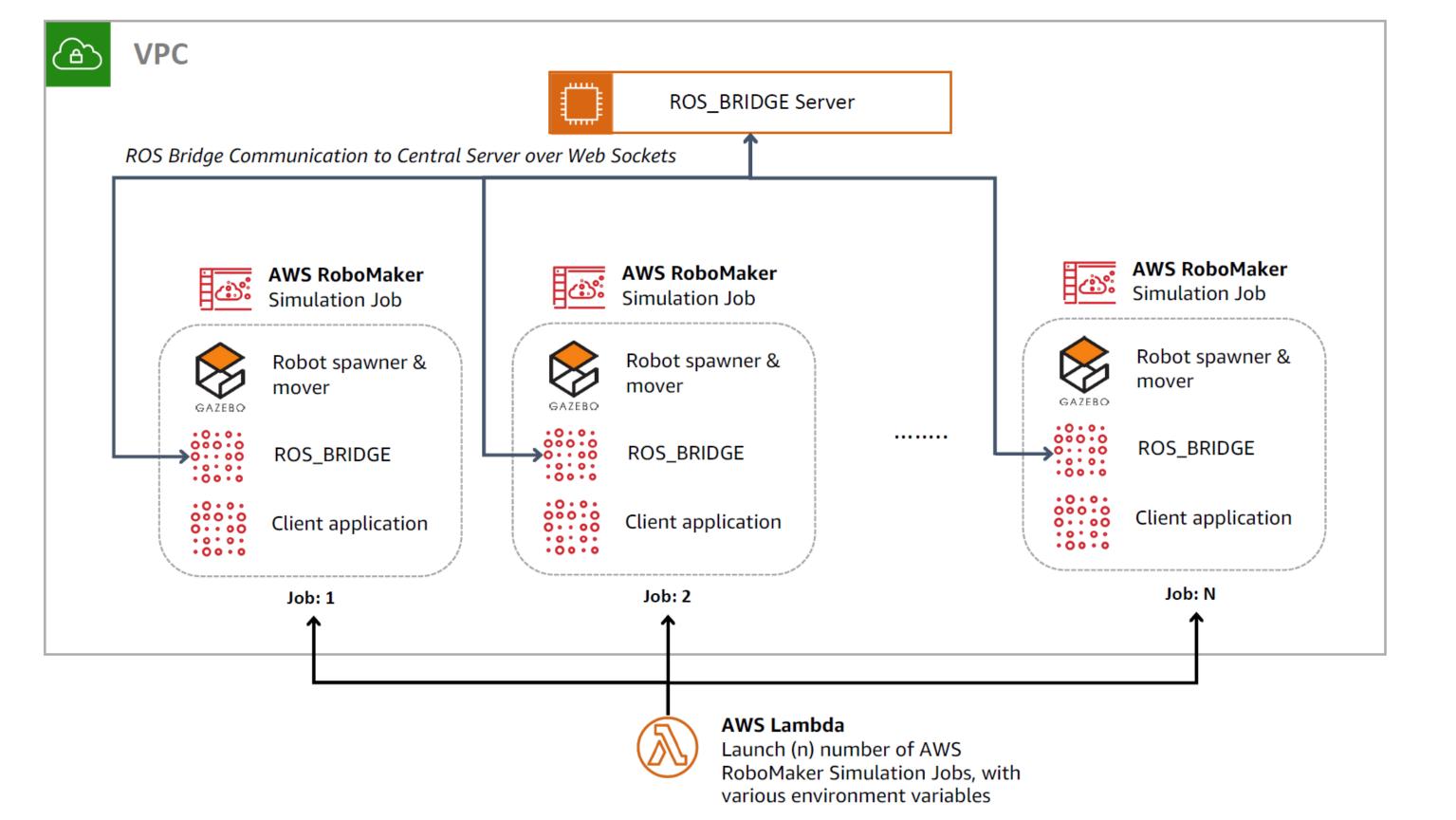
### Use of AWS RoboMaker

AWS enabled simulation of a multi-robot environment with 35+ robots, thus enabling testing without physical robots

AWS services used: AWS RoboMaker, AWS IoT Greengrass, **AWS Lambda** 

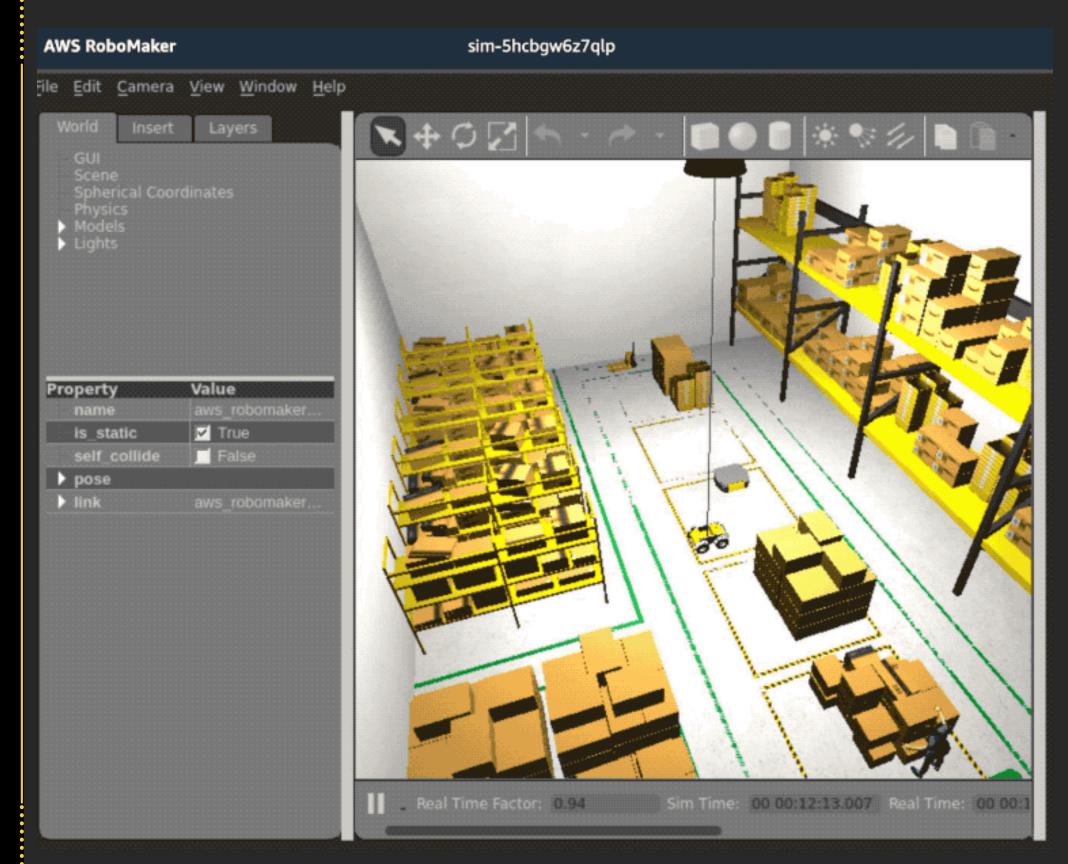
### **Business benefits**

Bastian Solutions easily able to test application for larger environments without having to stand up physical devices



# Multi Robot Simulation

contact: bargar@amazon.com to discuss rqmts!



## Simulation for **Model Training**

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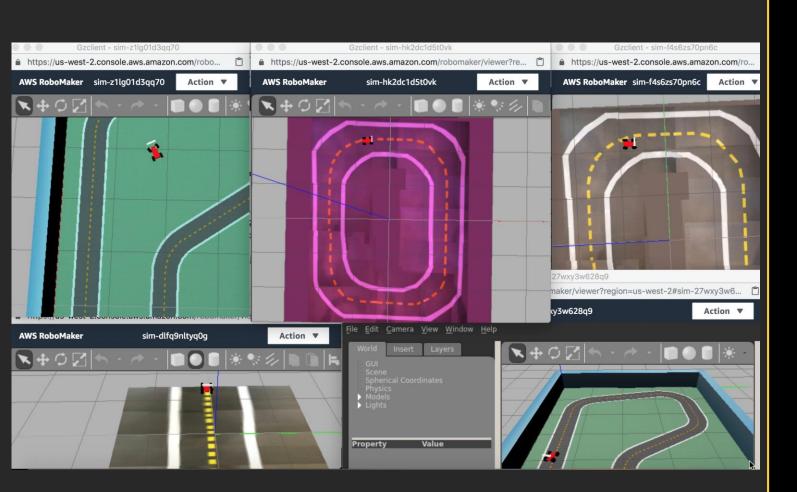
Rapidly generate trial data in simulation to train reinforcement learning model

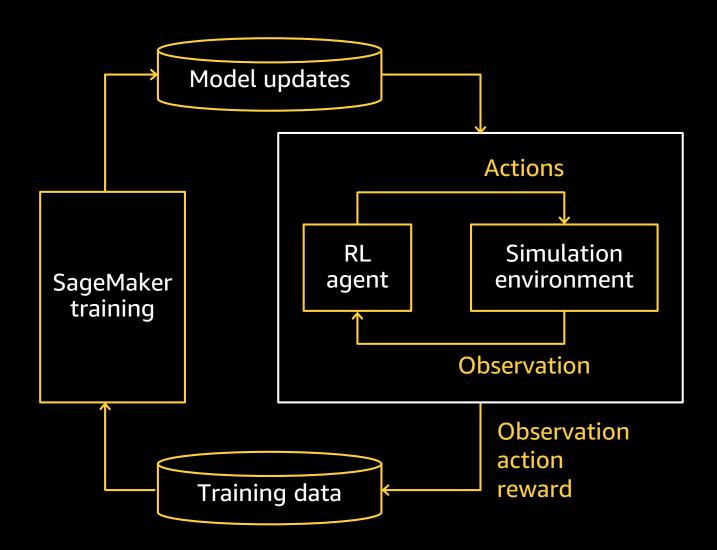
Train reinforcement learning model natively in the simulation or in AWS SageMaker

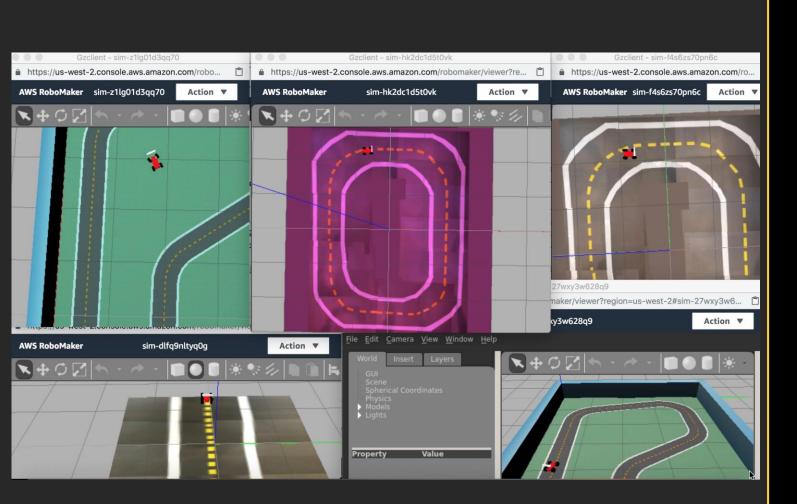
Run concurrent simulations to speed up training of a single model

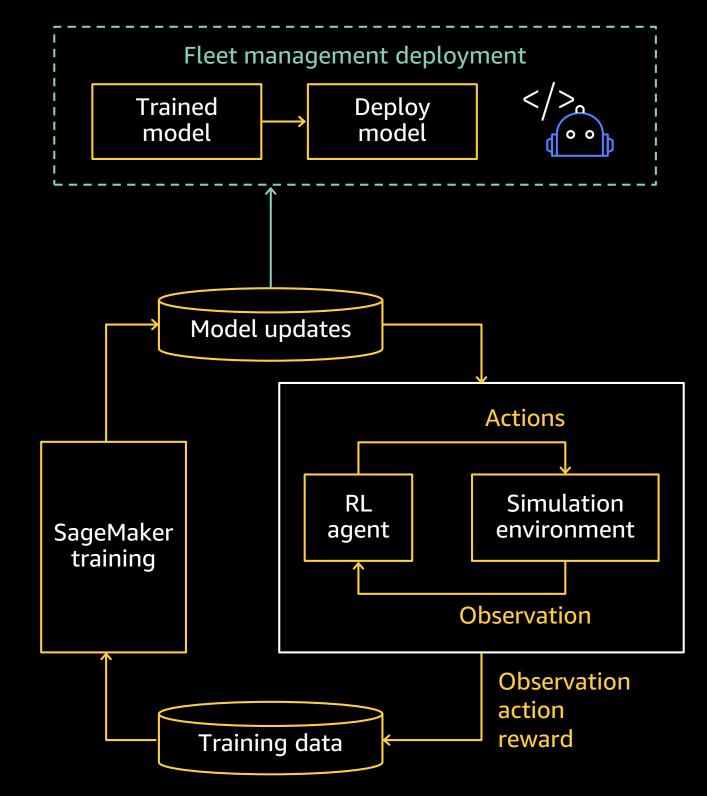
# AWS DeepRacer











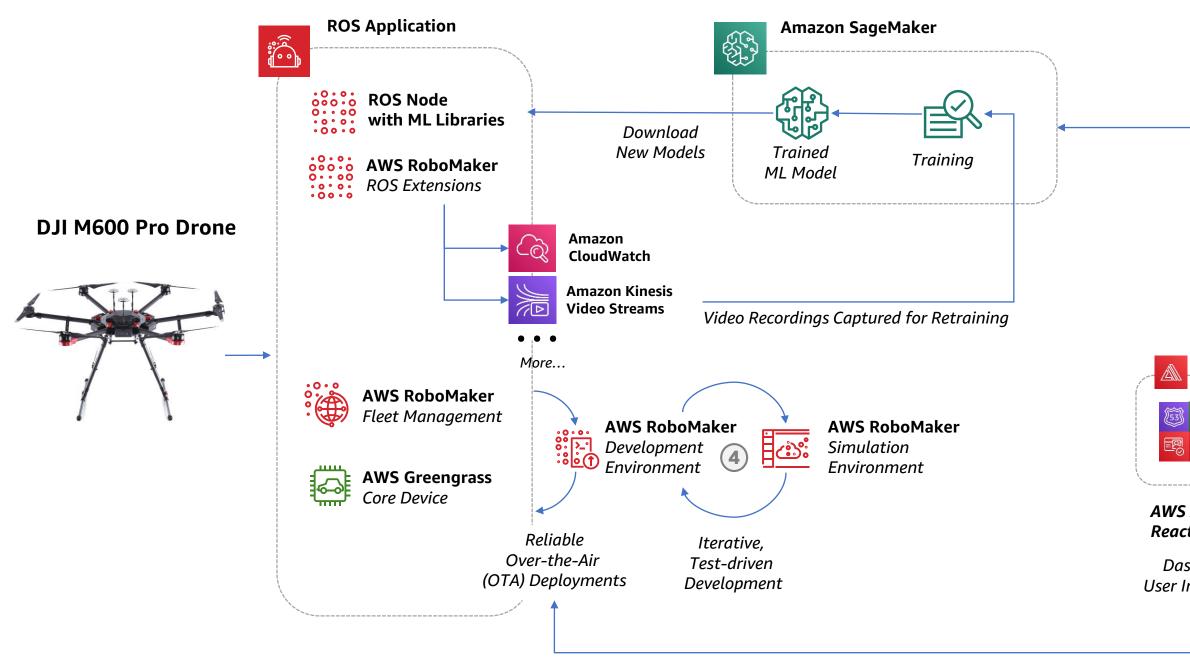
# Successful Transfer from Simulation to Real World







# Remote Monitoring Drone





### AWS Amplify React Website

Dashboard User Interaction Trigger New Model Training

# Robot Simulation Survey

Please take this short survey on requirements and desired features for simulation...

# https://tinyurl.com/rr6amyh



# **Deploy and Update** at cloud scale



Ability to control deployments



Visibility to robot health



## Enterprises need greater command and control over robot assets

### Deploy across multiple robot brands



# Deploy and Update

manage robots across multiple brands

### Problem statement

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Enterprise customers are unable to easily manage a fleet of multiple AMR brands

Inability to orchestrate across AMR brands Inability to share map information across robots

### AWS RoboMaker and AWS cloud services

Enable a unified interface to orchestrate robots and share maps across multiple brands

### **Business benefits** Ò

Ability to plan a mission across robot brands and robot types

Deploy and Update robot registration, over-the-air deployment with AWS RoboMaker

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Register robots with RoboMaker fleet management and organize them into fleets

Deploy a robotics application into a robot fleet securely through just a few clicks

Conditional over-the-air updates

Fleet monitoring and alerting\*

Fleet deployment rollback\*



## Aptpod Digital twin environment for AWS RoboMaker



### • Fusion Data Streaming Hub "intdash"

Provide data handling edge agent, sever APIs and visualization dashboard for industrial fusion data streaming Low latency bidirectional data streaming via cloud hub Simultaneously data acquisition and data analytics pipelines

### • Telemetry and Teleoperation

Rapidly develop Telemetry, Data Acquisition and Tele-operation functions into robots, simulation and physical environment

### • User benefits

Machine learning pipelines

"intdash" enables data acquisition of ROS messages

Data orchestration for machine learning on Amazon SageMaker

# Role of the Cloud

Intelligent cloud services can enhance local processing on the robot and improve performance over time.



Simulation can be used to test application correctness, and ensure performance across a range of conditions.



Simulation, combined with reinforcement learning, can be used to program robot actuation.



Cloud services enable developers to build applications for their business, end-to-end, that include robotics.

# Questions?

